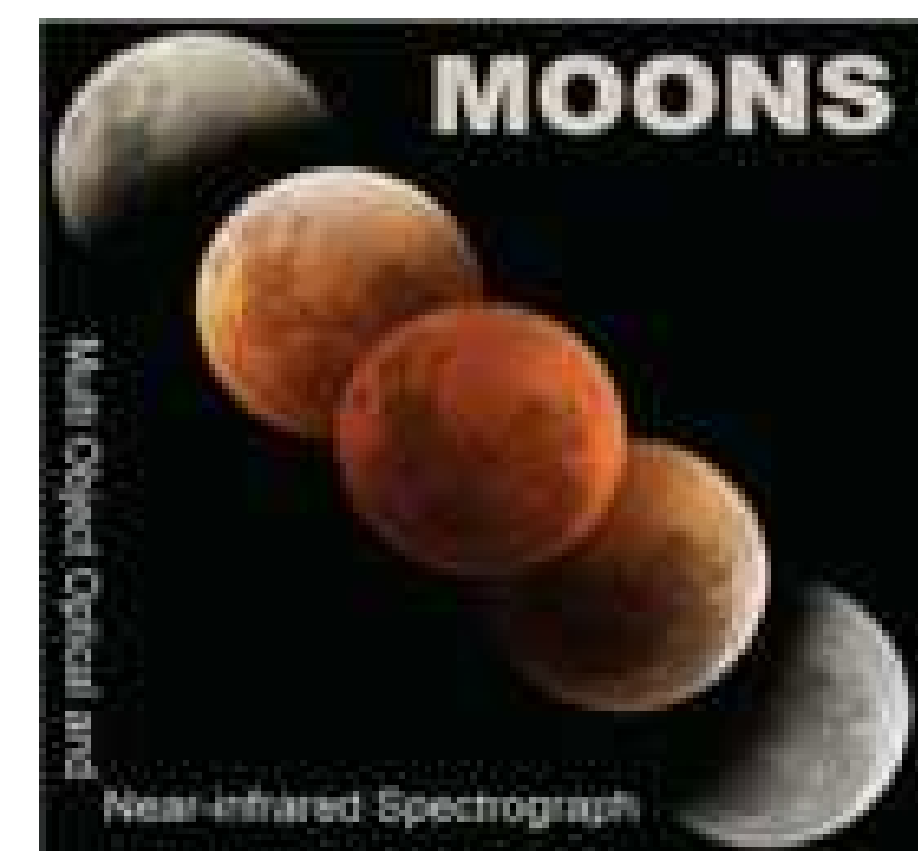




# Implementation and performance of the Metrology system for MOONS



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## INTRODUCTION

The Multi-Object Optical and Near-infrared Spectrograph (MOONS) will cover the VLT's field of view with 1000 fibers. The fibers will be mounted on two-arm robots to allow a homogeneous coverage of the 500 square arcmin field of view. To accurately and fast determine the position of the 1000 fibres a metrology system has been designed.

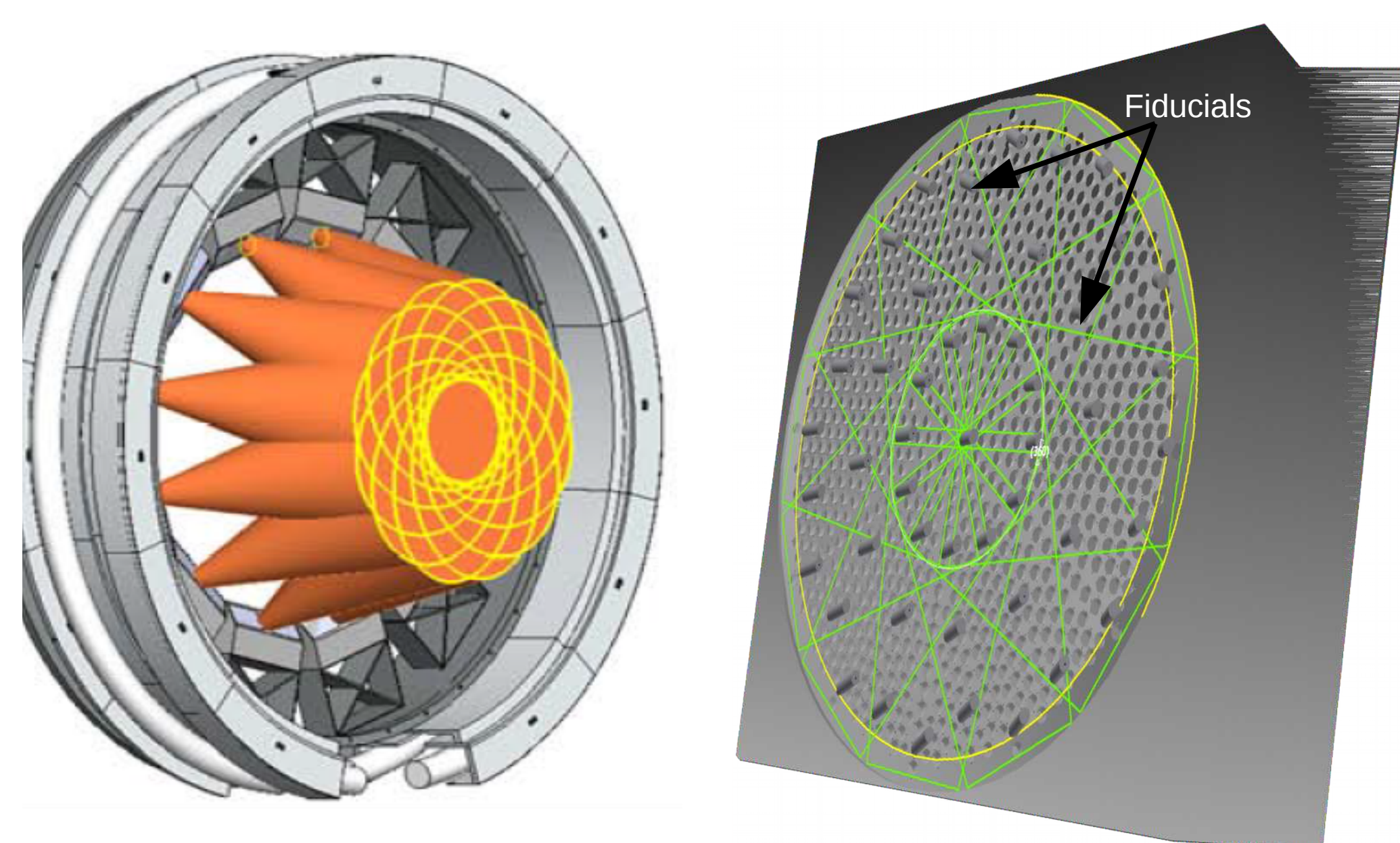


Fig. 1 Metrology system configuration. Left: 12 cameras in circular configuration with the observing direction marked in orange. Right: Observed fiber positioner support plate with fiducials and camera's fields of view marked in green.

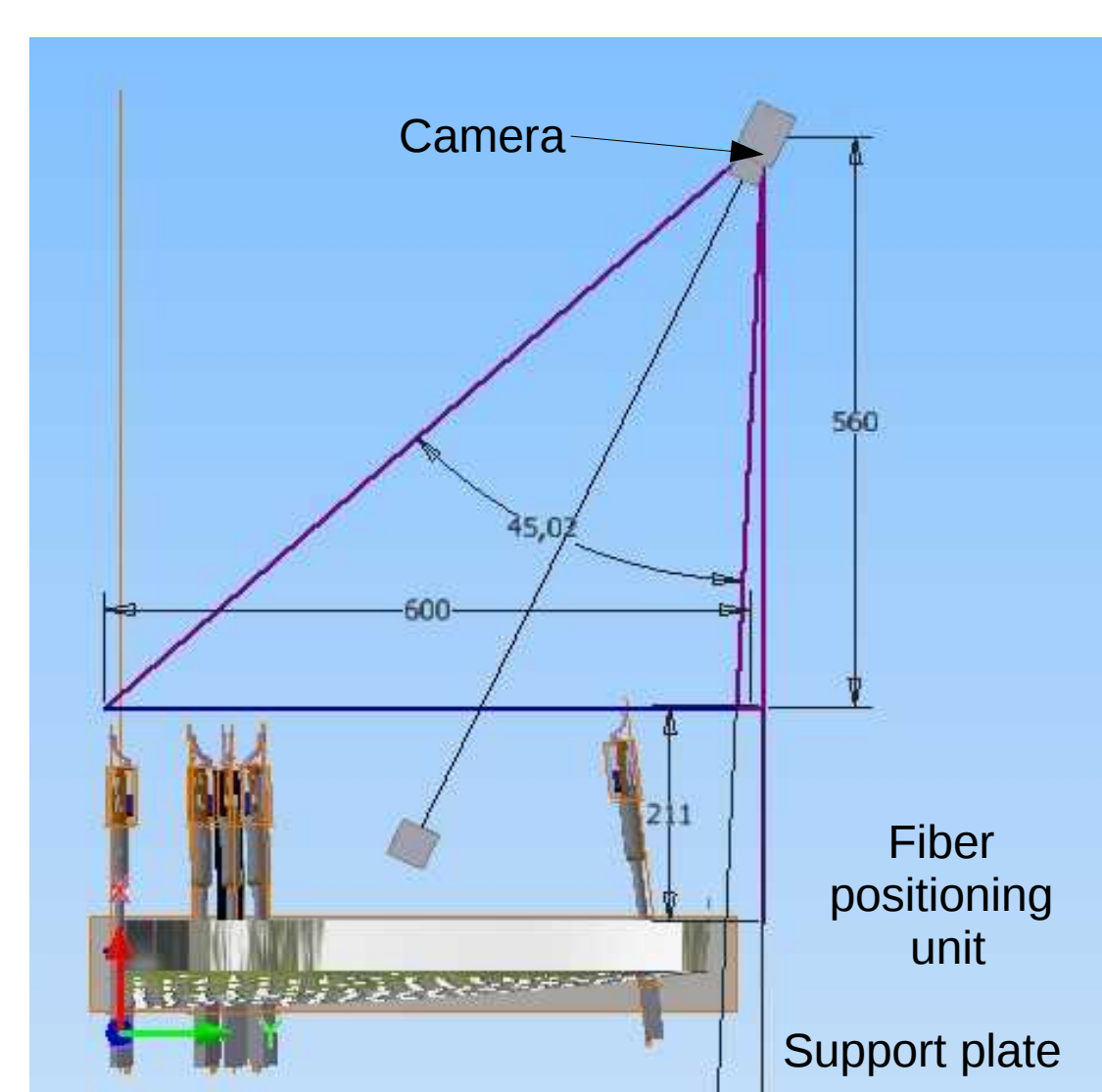


Fig. 2 Lateral view of the metrology system. Fiber positioner unit (FPU). Cluster of FPUs.

## METHODS

A combination of 12 cameras and 24 light with adjustable brightness provide ideally illuminated high-resolution images.



IDS UI-3590CP, 18M pixel, Resolution 8.3 px/mm

Metz mecalight LED-480



Fig. 3: From left to right: Metrology camera, Beckhoff light control, Metz metrology light

A flexible pipeline based on VLT standards is used to process the images.

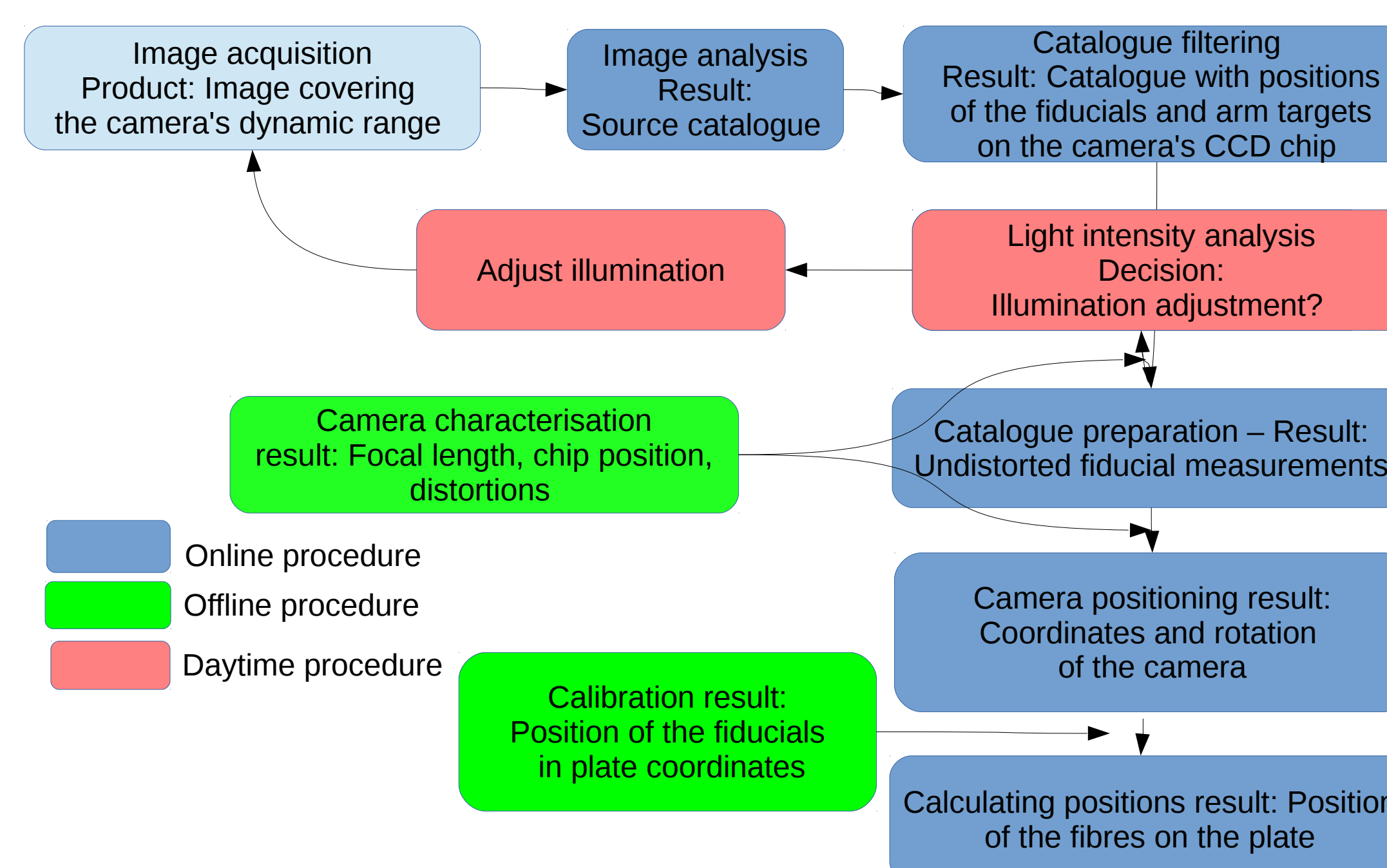


Fig. 4 Metrology Software pipeline

## RESULTS

The position accuracy was determined to  $\sim 5 \mu\text{m}$  in the central region of the images. Including the outer regions the overall positioning accuracy is  $\sim 25 \mu\text{m}$ .

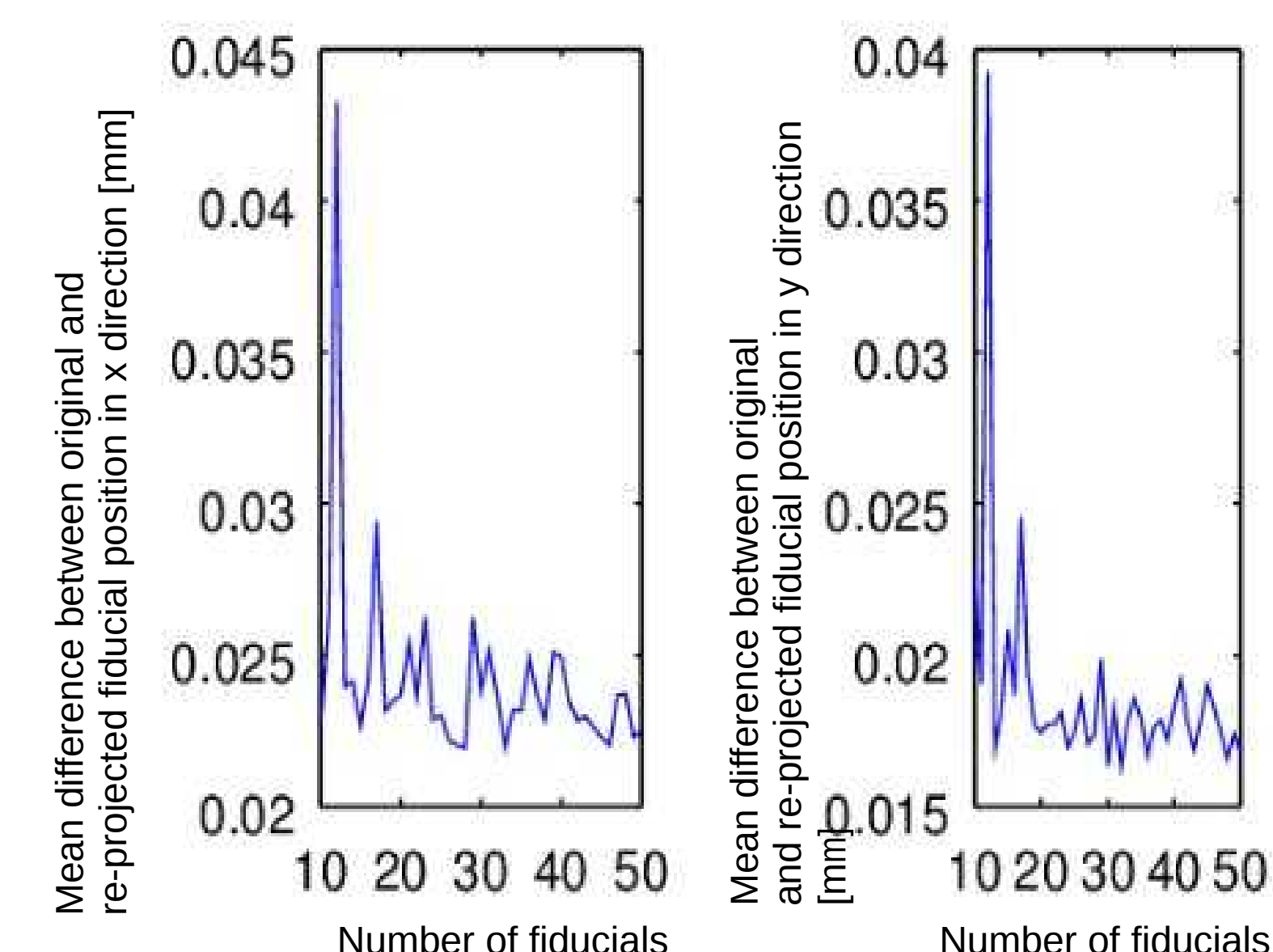


Fig. 5 Overall performance: Fiducial number simulation

## CONCLUSIONS

1. Results in the center of the image are excellent.
2. Further hardware improvement are on the way.
3. Integration into the VLT software environment is ongoing.

The MOONS metrology system is fully set up with a working prototype. By using upcoming hardware and improving the calibration it is expected to fulfill the accuracy requirement over the complete field of view for all metrology cameras.

## REFERENCES

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